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Debating the potential of Machine Learning in Astronomical surveys

Paris - 01/12/2023

Reionisation time field reconstruction and Model exclusion applied to WDM Julien Hiegel

Collab. with D.Aubert, E.Thélie, R. Ibata

Hiegel et al. (2023): arXiv:2307.00609





Part I

Introduction

Epoch of Reionisation: 21 cm maps

The **Epoch of Reionisation** (**EoR**) is the period where the universe transitioned from a **cold and neutral state** to a **hot and** ionised state due to the influence of the first sources of ionising photons (Stars, Galaxies,...)

During this epoch, the neutral hydrogen (HI) emits a radio signal (21 cm line) that will be observed with future radio observatories (such as the Square Kilometre Array SKA).



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(pure signal)

around z=5.5

Gyr

1.0

0.8

0.6

0.4

Epoch of Reionisation in a single field: t_{reion}



What is the Reionisation time field t_{reion} ? It is the time at which a given region reionised where the

value of each pixel represents the time [Gyr] of reionisation of this pixel

Local Reionisation process

The time of reionisation is not the same everywhere: The reionisation process is local and depends on the content of a given region.

Why this field?

 t_{reion} describes the whole reionisation history.

The **Reionisation seeds/Last regions to reionise** are related to the **minima/maxima** of this field (likely **densest/emptiest regions**).

We can study the **topology** of this field:

Typical size of ionised bubbles, Front speed, Abundance of reionisation seeds. Thélie+ 2022,2023

This is not an observable

How to recover it from observations?





21cmFast simulation code & Unet Architecture

In this work:

- ACDM cosmology (Planck+2020)
- Size of our simulations: 256^3 pixels for 256^3 cMpc h^{-1}
- Resolution set at 1 cMpc h^{-1} /pixel

18 redshifts: z c [5.5, 15]

For a **given map**: there is **18 version** of it (1/redshift) describing its temporal evolution and these **18 maps** share 1 t_{reion} map.

50 simulations lead to 768x50 = 38 400 images that compose

the whole data set -

We need to divide this into **3 subsets**: For each z (x18)

For each field (x2)

Training set (Learning phase: **compute loss** and **update weights**)

- Validation set (Learning phase: compute loss only)
- **Test set** (Prediction phase: output maps inference)

A trained CNN at a given redshift = 1 predictor



Part I

Results

Reconstruction of reionisation time map



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Part I

Results

Reconstruction of reionisation time map



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Comparison between redshifts of observation

R^2 coefficient computed on the validation set:

• For z < 7:

The performances are bad:

- Non-zero signal fraction < 40% in 21 cm maps</p>
- There is zero signal inside ionised bubbles that became large at this range of redshift
- Optimal performance for z = 11:
 - In our simulations: This is the best compromise between
 - Number of ionised bubbles that is sufficient to locate the reionisation seeds
 - ⇔ Size of bubbles that is not too large to get a significant amount of signal fraction

• For z > 11

performances get slightly worse with increasing redshift: fewer ionised bubbles = We can locate fewer sources

The performances are globally satisfying:

ightarrow 21 cm maps contain the reionisation time information



Results

Instrumental effects and CNN's performance

New predictor for z = 8 trained with noisy 21cm maps made with SKA characteristics using tools21cm (Giri+2020), assuming (Prelogovic+2022, Ghara+2016, Giri+2018):

- Daily scan of 6h and 10s integration time and for a total of 1000h of observation
- A maximum baseline of 2 km
- Angular resolution of $\Delta\theta\sim 2.8~\text{arcmin} \Leftrightarrow 7.35~\text{cMpc}$ at this redshift

The **prediction is significantly altered** compared to the perfect observation scenario:

• Large-scale structures are less prominent, appearing buried or obscured and a lot blurrier



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Results

Instrumental effects and CNN's performance fraction of neutral Hydrogen

 t_{reion} allows to reconstruct the average neutral fraction history $Q_{HI}(t)$

For 21 cm maps without noise: (red) The predictor gives a satisfying reionisation history

For noisy observations: (blue)

The predictor **starts** the **reionisation later** and tends to **finish it earlier** than true field.

-> It suffers from the smoothing since the extrema are erased.

Nevertheless the reconstruction of the global reionisation history is satisfying



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Questions



What happens when **some data is given to a "wrong" predictor** (with wrong underlying model)??

 → Ideally data given to a predictor with the right model should give the same t_{reion} map no matter the redshift of observation
 → We may compare results at 2 redshift of observation

If we notice an inconsistency between 2 reconstructions at 2 different observation redshifts, Can we then use it to exclude predictors ??

→ A model is linked to each predictor: excluding a predictor means excluding a model

We test this method to exclude WDM models (work in progress)

Methods

Results

CDM Model VS Predictors

We arbitrarily set one model as reference: CDM is in this study our mock observations.



Methods

Results

CDM Model VS Predictors

We arbitrarily set one model as reference: CDM is in this study our mock observations.

By training CNN with **DM models (3keV, 5keV, 7keV, CDM) and z = 8, 11**: We get a list of **predictors** that have their **own model**.

Identical CDM model as previously <u>Ex</u> WDM models have a <u>similar reionisation scenario</u>

Example: We have 2 Predictors for the model WDM 3 keV 1 for each redshift (8 and 11)



Lower limit on the thermal relic WDM particle mass:

Iršič+2023: **5.7 keV** (Ly α) **Enzi+2021**: **6.048 keV** (Strong Grav. lensing, Ly α, MW satellites) **Nadler+2020a**: **6.5 keV** (MW satellites)

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Thanks to the mock observations (CDM), we infer t_{reion} with each predictor (For the 4 DM models and for the 2 redshifts).



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We compare the predictions and estimate whether the predictor fits the observation -> Model Exclusion.



Part II

Introduction

Method

Results

Autoconsistency check with t_{reion} isocontours



Autoconsistency check with t_{reion} isocontours total Length L Work In progress (Hiegel+ in prep)

For a given predictor, as the predictions should be statistically identical we should have the same isocontours for z=11 and z=8

Then we compare the isocontours total length from z_{obs} =11 and z_{obs} =8 to test the auto consistency of a model: Here even the CDM isn't perfectly auto consistent



Conclusions

Reionisation time recovery: arXiv:2307.00609

The reionisation time field information is encoded in the 21 cm signal and we can reconstruct t_{reion} from 21 cm maps

The predictor performance depends on z_{obs} for a given reionisation scenario and there is an optimal z_{obs} . We get good reconstruction at large scales, however there is small scales issues

Predictions with **noisy observation** are in broad agreement with ground truth at large scales but the **smallest** scales are totally missing on the prediction

Model Exclusion applied to WDM models: Work in progress

We can exclude models of WDM with 2 observations but **it requires more investigations to get more quantitative results**

Perspectives

How to recover smallest scales and increase general performance ??

Generative Adversarial Networks (GANs) might be a solution (Ullmo+ 2020) Implementing Attention Block to improve feature extraction can boost the performance (Chen+ 2016)

How can we Validate/exclude the underlying model of a predictor ??

What metric (e.g. **P(k)**, **Npeak**) can we use to exclude models ? Can we give a **score** that tells the **confidence** we have in a given predictor

Is this exclusion process viable with noise?

Overview of the Universe history





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21cm signal and Square Kilometer Array (SKA)





SKA-low antennas – Credit: https://www.skao.int/en/explore/telescopes/ska-low

SKA-low (late 2020s):

130k+ Antennas in Australia
0.4 km² collecting area
Frequency range: 50-350MHz

It is the necessary range to observe the 21cm line through the EoR





MSE – Coefficient of Determination R²



The determination coefficient is defined as :

$$R^{2} = 1 - \frac{\Sigma(Pred - True)^{2}}{\Sigma(True - \langle True \rangle)^{2}}$$

This coefficient tends to 1 for a perfect correlation between the prediction and the ground truth

$\underline{R^2}$ coefficient computed on the validation set:

- Bad performances for low redshift: z < 6.5 \Leftrightarrow signal fraction < 40%
- Optimal performance for z = 11
- For z > 11, performances get worse with increasing redshift

Results

2D Power Spectrum of reconstructed t_{reion}



Reconstruction for observation at **redshift<8** fails at early and late times

z>8 predictors give a relevant history of reionisation.



computed from **T21 maps** as the signal fraction, agiven marker depicts thefraction of HI Q_{HI} at a givenredshift using observations at this same redshift

→ This information is contained in the line of sight

Dashed area and dotted lines:

Computed from **time of reionisation maps** as the cumulative PDF

→ This information is contained in the sky

Line of sight and plane of the sky are in agreement



Results

True Versus Prediction





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True t [Gyrs]

Part II WDM Models 21 cm Maps

In WDM models: There is fewer structures than for CDM depending on the mass of the WDM particle t_{reion}

z=8

What happens for the 21 cm signal?

21 cm map at z = 11

As the **mass** of WDM particle decreases:

-> Missing regions

 -> In general the distribution of temperature is different because the reionisation timing is different



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Part II

WDM Models Reionisation Time Field

Similar reionisation scenario

Same parameters as previously used for CDM scenario (ζ 30) except for 3keV: ζ = 32

Reionisation **begins and ends** around the same times **z = 15 and 5** respectively

WDM models have a **delayed mear** reionisation time







Predictions: CDM vs WDM Predictors

In practice:

- Predictions for z=11 and z=8 should be statistically similar
- Predictions for all models should give the same result

→ 7keV and CDM look similar → Not the case for z = 11



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Part II

Results

Power Spectrum: Comparison to true CDM



Power Spectrum: WDM vs CDM

We compare **predictions of each model** with predictions of **CDM** -> **CDM is the reference**, we should get **similar results**.



Part II

Introduction

Aims

Results

Integrated Power

From CDM predictions: We can obtain the mean and std of the power spectrum and integrate it for a given k range:

-> We obtain our **reference** where the predictions **should be located**. (**red and blue bands**)

We perform the same transformation for the predictions of each model



Integrated Power

CDM matches with the reference (Fortunately, the reference is the CDM !) **7keV** matches as well with the reference: Cannot conclude anything **5keV** matches when z=8 but differs for z=11: Need to confirm with another metric **3keV** is off limits: This model is **excluded**



What is the **meaning** of an **integrated power**? Results are dependent of the k range chosen

Integrated in k range: [2e-1:5e-1]



21cmFast simulation code: *z*_{*reion*} Vs *t*_{*reion*}



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21cmFast simulation code: *z_{reion}* Vs *t_{reion}*



Convolutional Neural Network: U-net Architecture



21cmFast simulation code: image extraction process



Example of the process to extract Images from a box of size 16^3 using a spacing of 2 pixels

For a single simulation (= 1 box of volume 256^3):

• Divide it into 8 cubes of size 128³

For each of cube:

Extract 32 evenly spaced (4 pixels) slices (128²) in each direction (x,y,z)

Resulting in 96 images for each cube of size 128³ Leading to 768 images for 8 cubes (= 1 simulation)

To account for different redshifts used in the training of the CNN, this number is multiplied by 18

There are 2 cosmological models, further increasing the total number of images by a factor 2

The dataset used in this work consists of **50 simulations**, resulting in a total of **38 400 images / field (x2) / redshift (x18) / reionisation model (x2)**

<u>Note</u>: for t_{reion} we don't multiply by 18

Convolutional Neural Network: Training Phase



Convolutional Neural Network: Validation Phase



During the Validation phase that takes place after each epoch, the algorithm compute the MSE and the R^2 coefficient on images that the predictor has never seen

Nevertheless, the weights are not updated at this step

Convolutional Neural Network: Testing Phase



The testing phase takes place when the predictors are set. It is now used to predict the time of reionisation from the temperature brightness. We now can use the predicted fields to measure parameters and compare it via several metrics to the ground truth given by the simulation